



Congestion-aware Distributed Task Offloading in Wireless Multi-hop Networks using Graph Neural Networks



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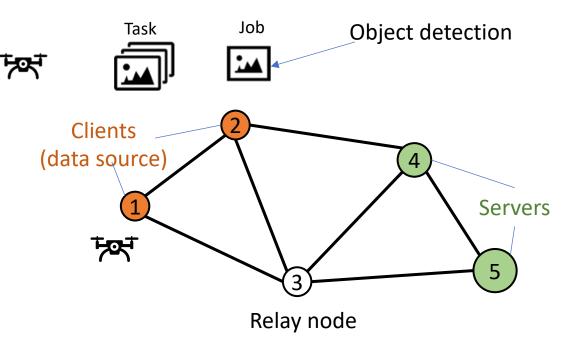
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Distributed task offloading

- Wireless multihop networks
 - Clients: data source, resource-constrained
 - Relay: well-connected, no computing
 - Servers
- Task: a steady flow of similar jobs
 - Same job type (object detection)
 - Same job data size (a video frame)
- Client decision-making
 - Location: which server to do computing
 - Routing: path to the selected server
- Multiple clients make parallel decisions in a batch
 - Streaming based on per-task decisions
 - Minimize average job response time

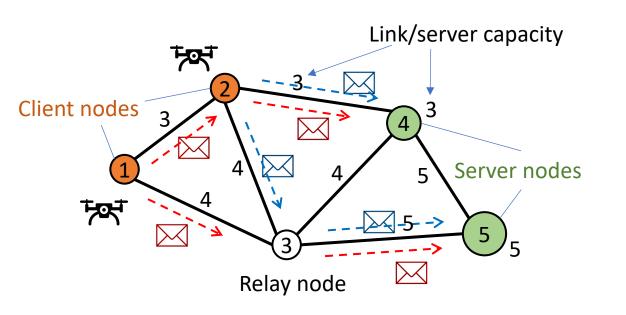




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Baseline: context-agnostic distributed offloading



Step 1: clients send out probing messages

$$\delta = \frac{1}{r}$$

Step 2: clients send **task flows** via "the shortest path" to the virtual sink

Minimize task response time

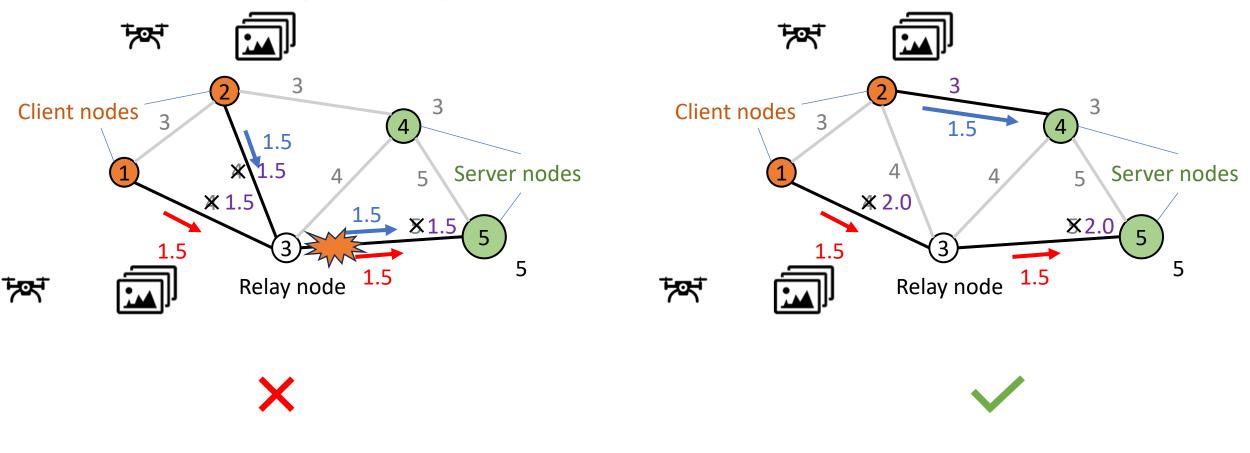
Consider per-link unit delay as edge weight







What could go wrong in wireless networks?



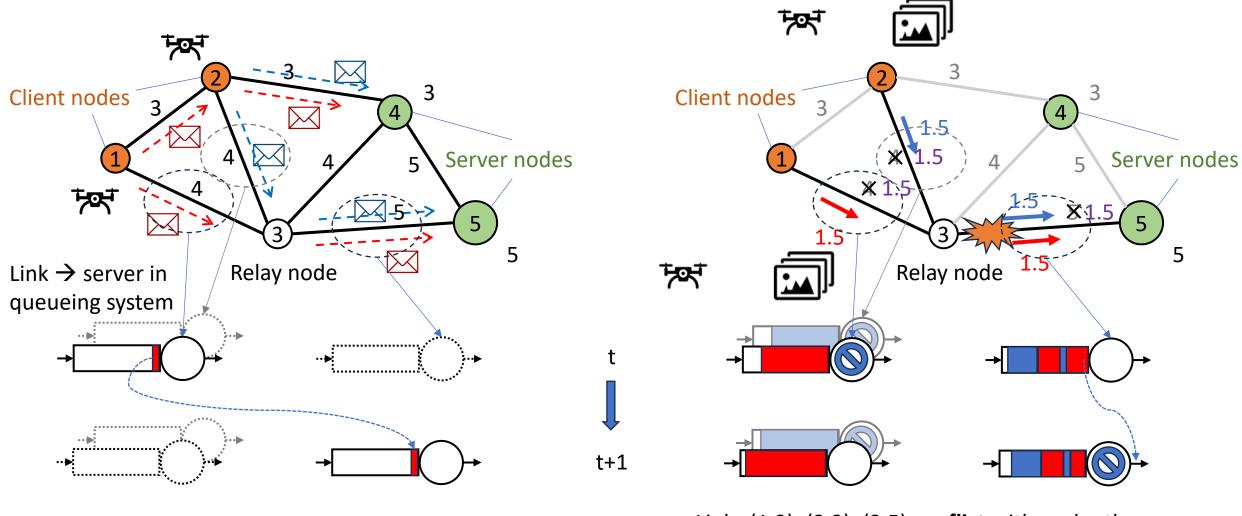
Link capacity changes once the streaming begins, depending on path selection & flow rate assignment







Queueing networks with interference constraints



probing messages are **short-lived** flows

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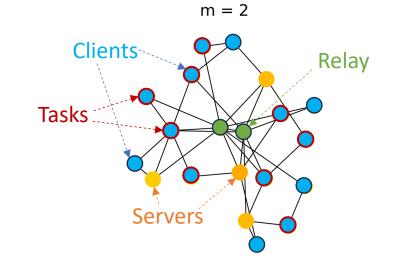
Links (1,3), (2,3), (3,5) **conflict** with each other, since node 3 has only one radio interface





Alternative decision frameworks

- Distributed greedy decision
 - Shortest path
 - Low communication overhead
 - Congestion/collision
- Centralized scheduler
 - High communication overhead
 - Single point of failure
- Peer coordination between clients
 - Difficult for large networks
 - High communication overhead

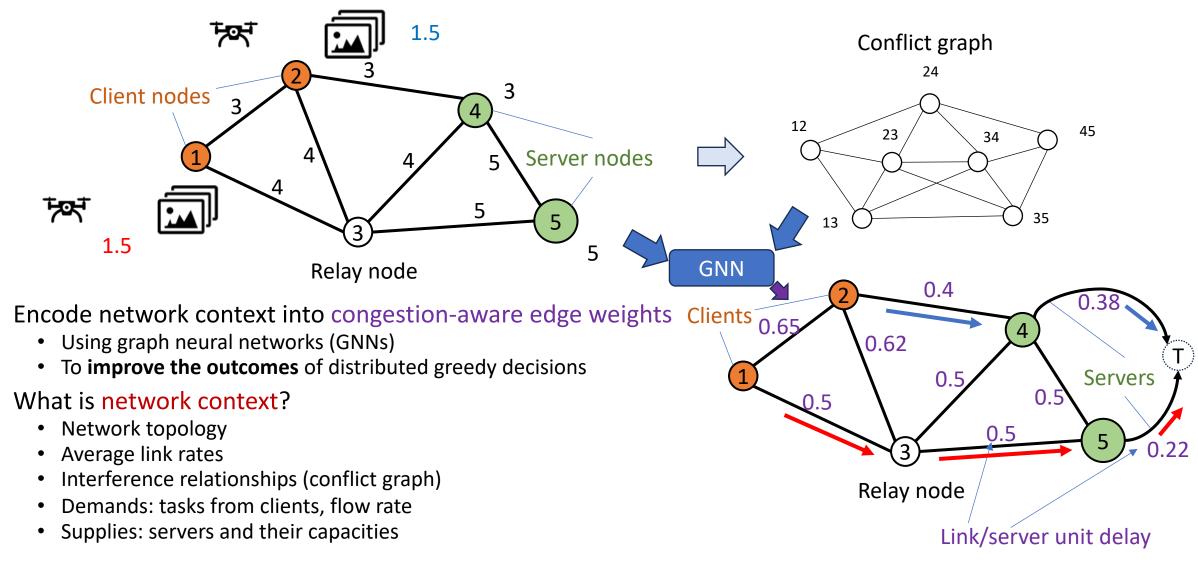








Our solution: keep shortest path decision, change *edge weights*



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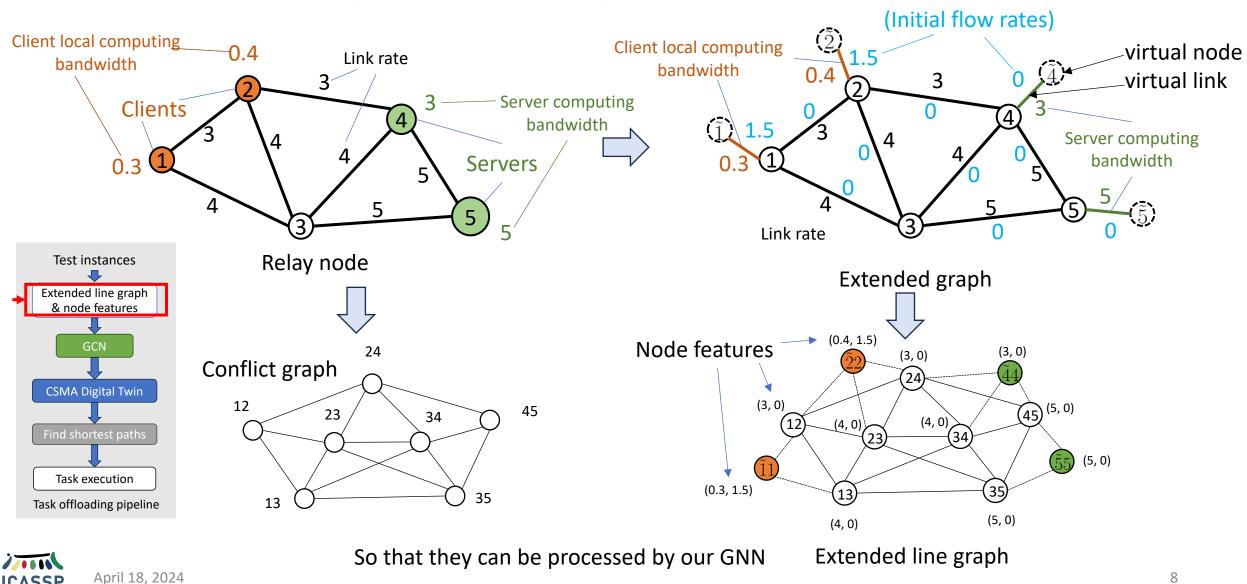
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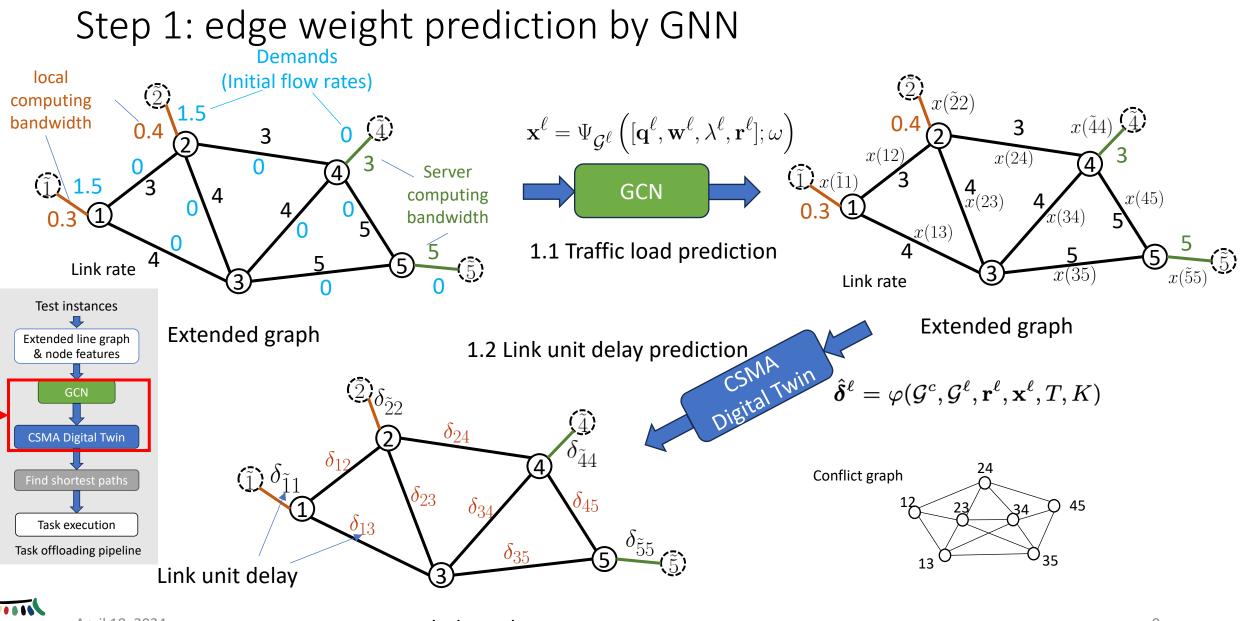
Demands

Our solutions: graph modeling



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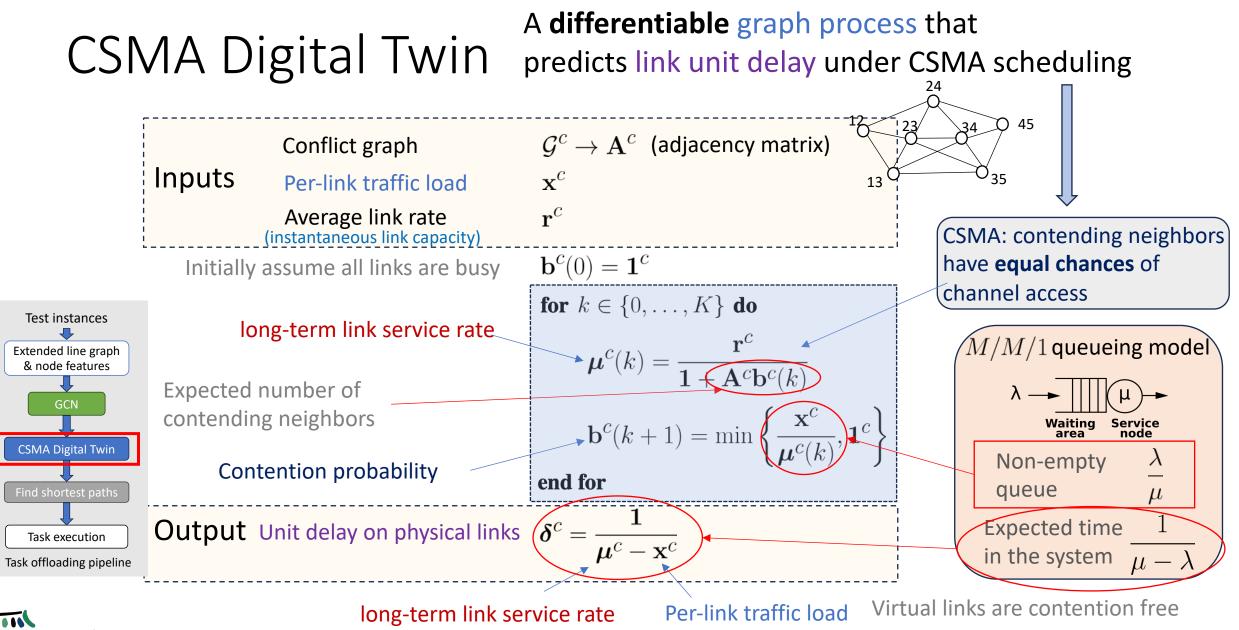
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Extended graph

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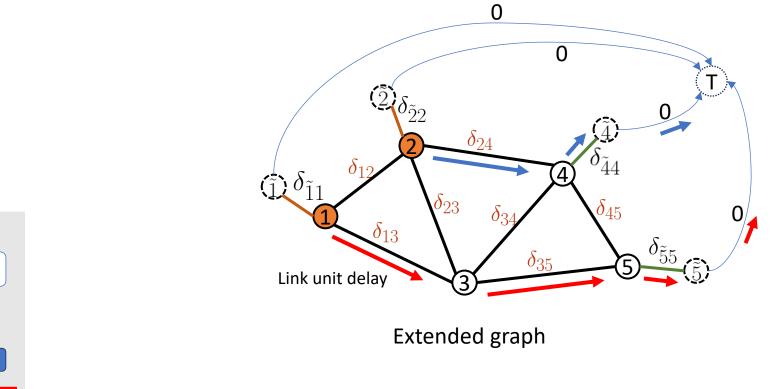


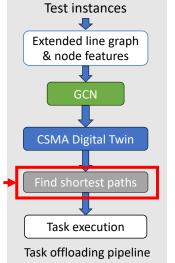
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Step 2: distributed offloading & routing decisions





Clients (nodes 1, 2) find their own shortest paths to the virtual sink

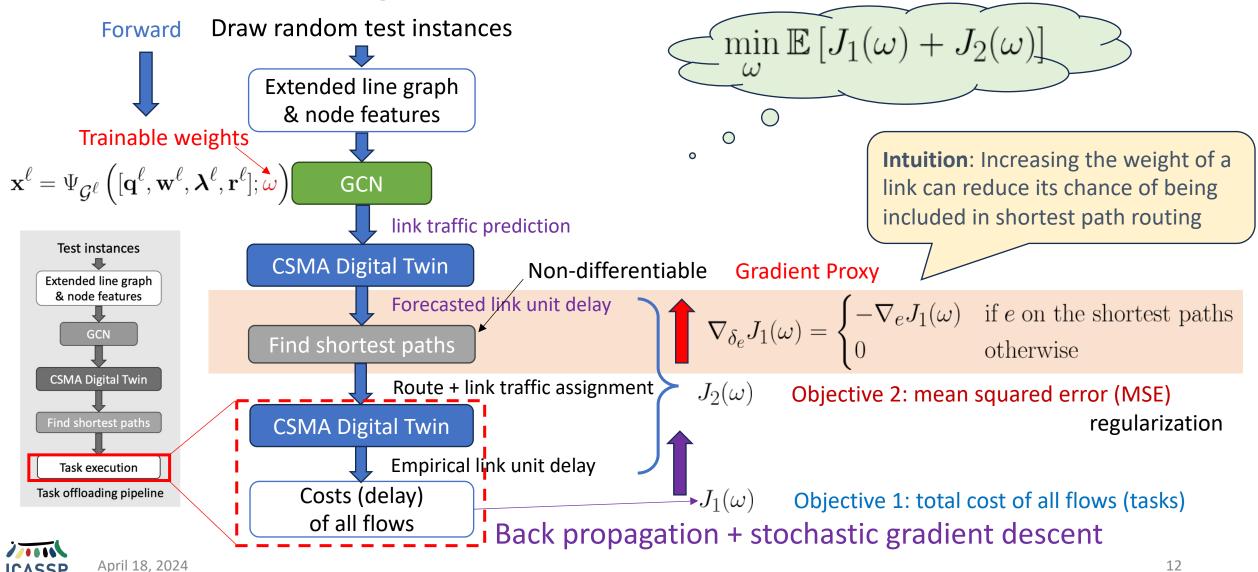




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GCN training



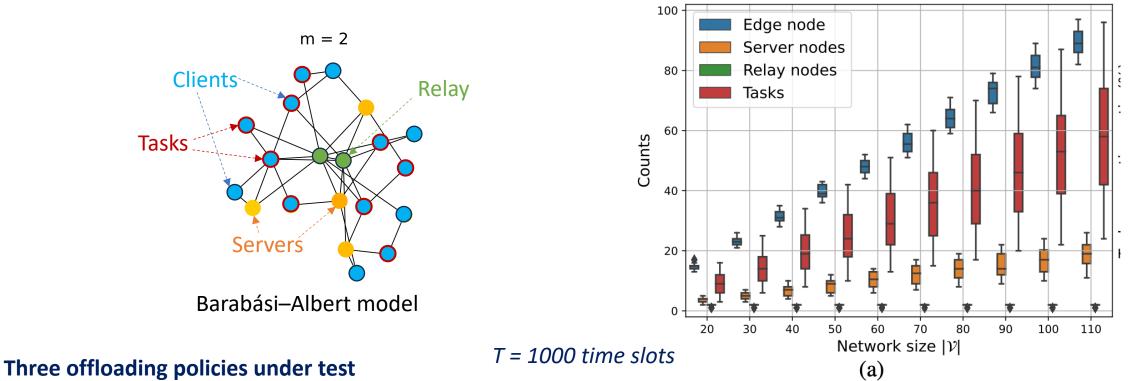




10 network sizes x 100 graphs x 10 offloading instances

Numerical experiment

Random network topology and offloading instances



Local: every task is executed at its source client node GNN: distributed greedy decisions based on link/server unit delay predicted by GNN Baseline: distributed greedy decisions based on (1/link rate) – network context agnostic

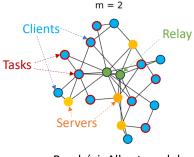






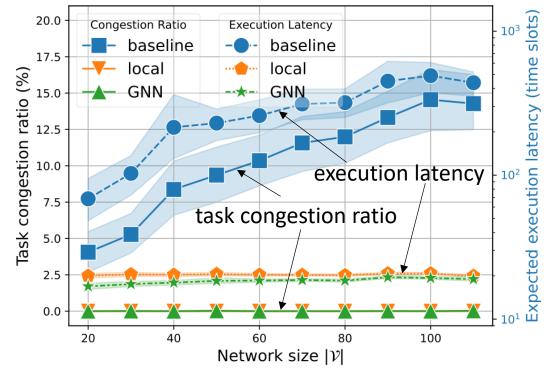
T = 1000 time slots

T = 1000



Barabási–Albert model

Numerical results



If a task is congested, its execution latency > 1000 time slots

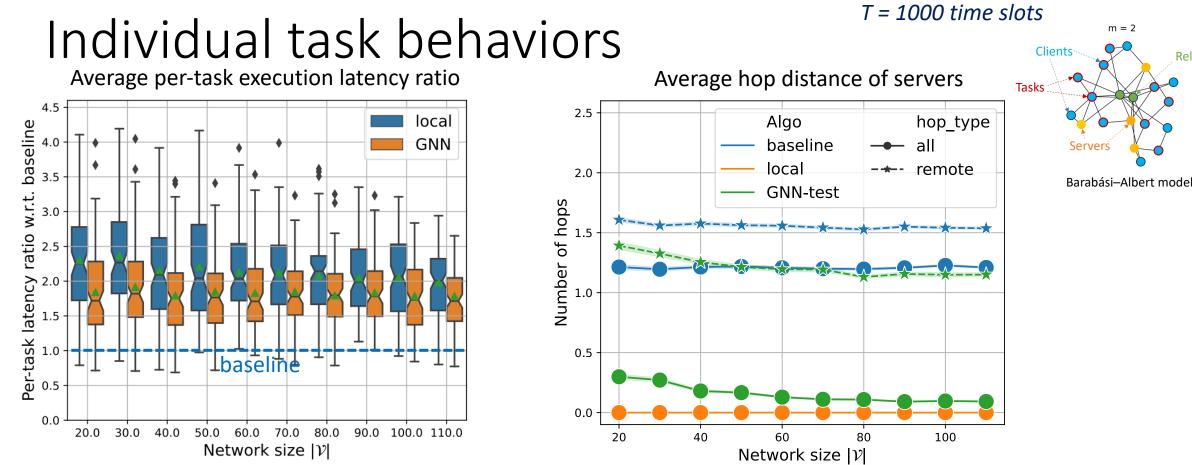
Local: all clients can execute their own tasks without congestion GNN: some tasks offloaded to remote servers without congestion, reducing average execution latency compared to the local policy Baseline: 4%~15% congestion ratio, and high average execution latency (500)







Relay



What about tasks that are NOT congested under the baseline policy?

- Baseline policy yields the lowest average execution time ٠
- GNN is still better than local policy ٠
- GNN favors nearby servers ٠
- The result is still preliminary, GNN could be further improved! ٠

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Conclusions & future work

- Distributed task offloading + routing \rightarrow shortest path routing
- Encode network context into edge weights
 - Graph convolutional neural networks
 - CSMA digital twin
- Mitigate congestion of concurrent flows of jobs
- Future work
 - Decision framework: iterative, probabilistic
 - Improve training approach
 - Trainable digital twin for other link schedulers
 - Evaluation on simulated queueing networks

