



Delay-oriented Distributed Scheduling using Graph Neural Networks



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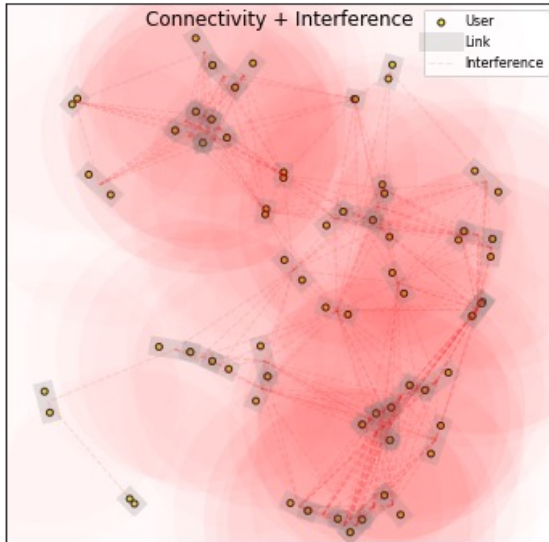
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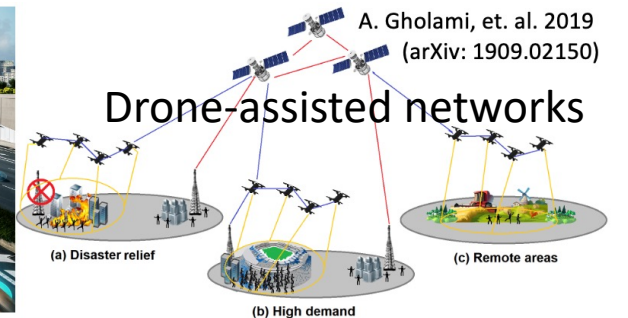
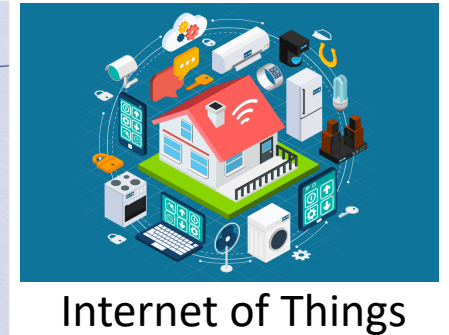
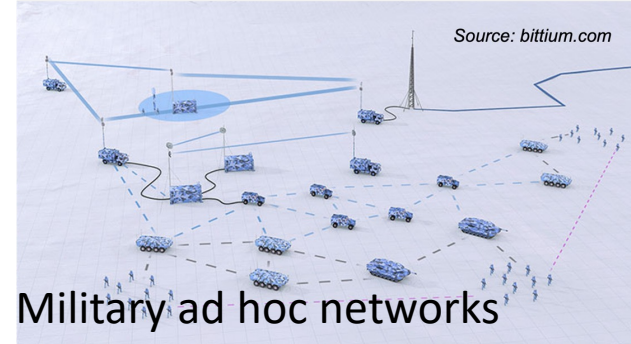
Singapore, 22-27 May 2022

Wireless Multihop Networks



No base-stations!!

- Autonomous, self-organizing nodes
- Mobile Ad-Hoc Networks
- 5G and beyond
 - Wireless backhaul networks
 - Traffic offloading



Distributed Scheduling Basics

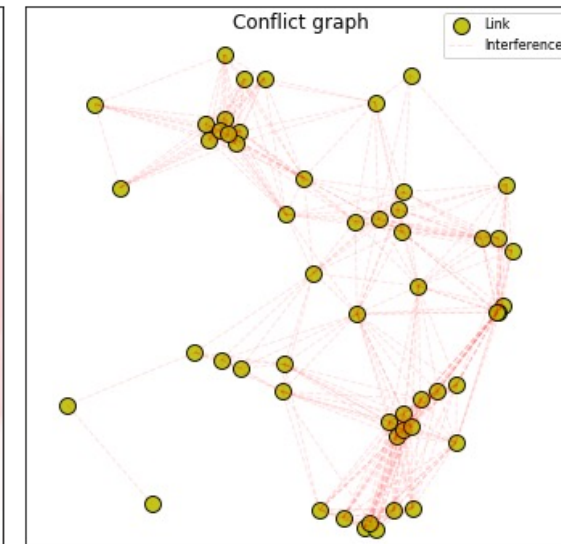
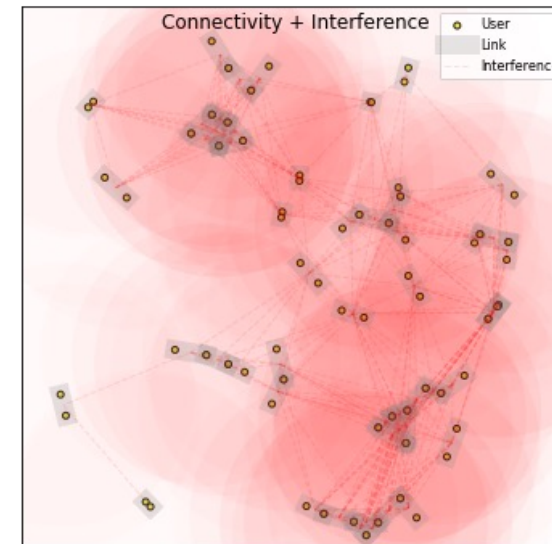
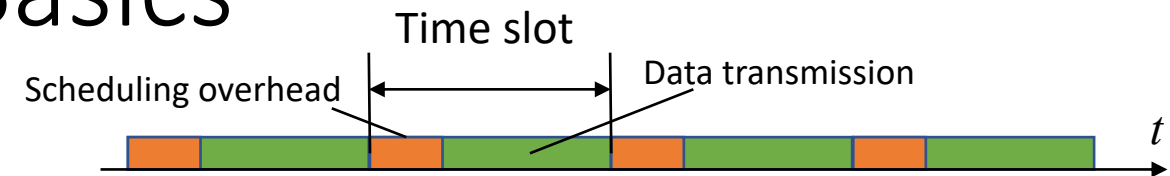
- Time-slotted network
- Conflict graph
 - Interface conflict
 - Potential interference
- Orthogonal access
 - Independent set on conflict graph
- Maximum weighted independent set (MWIS)
 - Node weight: per-link utility function
 - Independent MWIS problems across time slots*
- Optimal scheduler v.s. heuristics
 - Optimal: NP-hard (discrete optimization)
 - Local greedy scheduler (LGS) [Joo 2012]

Throughput-maximization

* S. Basagni, "Finding a maximal weighted independent set in wireless networks,"
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Delay-oriented Distributed Scheduling using Graph Neural
Networks, IEEE ICASSP 2022

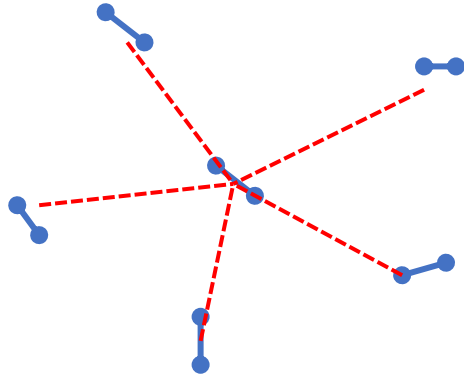


	Synchronized	Random Access
Infrastructure	Cellular, 5G (19.6%)	Wi-Fi (51%)
Ad-hoc	Wireless Ad-hoc networks (military, backhaul, mobile)	Wireless ad-hoc & sensor networks

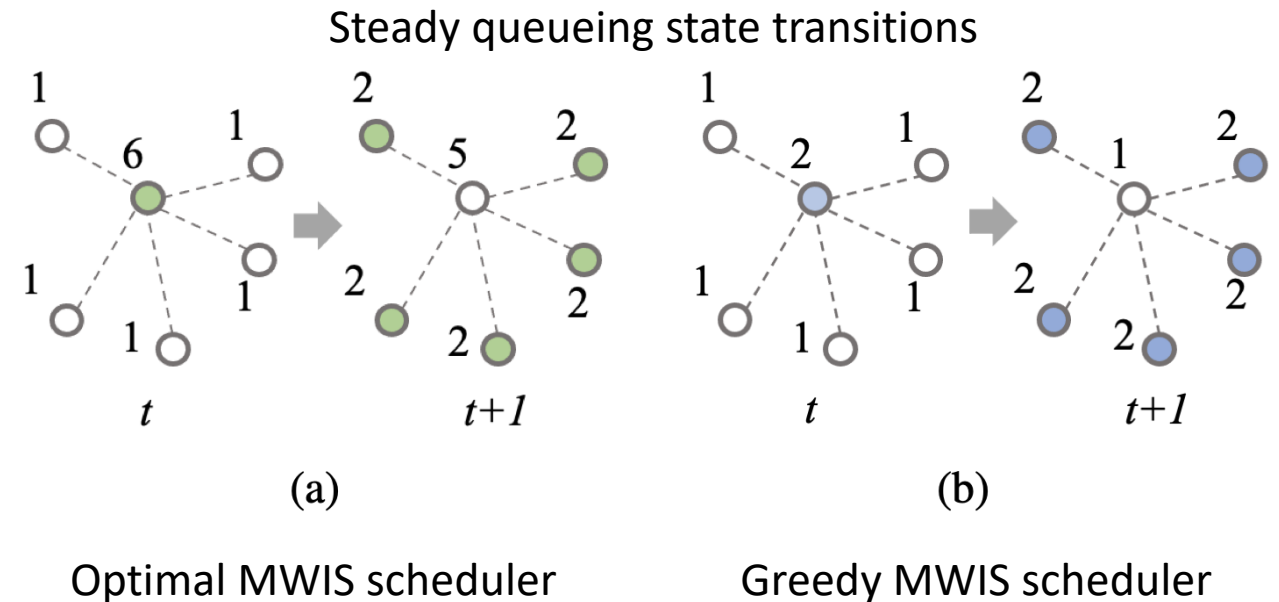
Self-organizing MAC

Source: Cisco VNI Global IP Traffic Forecast, 2017–2022

Latency: Optimal v.s. Greedy Schedulers



- Star conflict graph
- Per-link utility: Queue length
- Arrival rate: 1 packet/slot
- Link capacity: 2 packets/slot
- Initial state: all queues empty



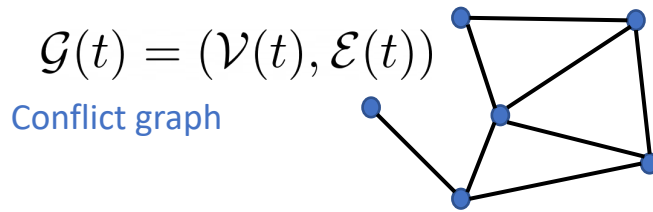
$$\bar{q}_{opt} = 2.17$$

$$\bar{q}_{grd} = 1.5$$

Queue-based per-link utility leads to poor delay performance

Problem formulation

1. MWIS is NP hard
2. Stochastic arrivals and link rates
3. Dependence between time slots



Moser-Tardos Algorithm *
(CSMA, LGS[Joo 2012])

Scalability $\mathcal{O}(\log^* |\mathcal{V}|)$

$$\hat{\mathbf{v}}(t) = h(\mathcal{G}(t), \mathbf{u}(t))$$

Analytical utility functions

virtual queues of congestion [Xue 2012],
sojourn time [Hai 2018],
age-of-information [Hsu 2017]

Machine Learning generated utility

MLP outputs utility [Gupta 2020]

GCN outputs utility [This work]

Leverages
Topology

MLP outputs decisions [Lee 2021]

Problem 1. For a time horizon of interest T , we want to solve for the delay-optimal scheduler given by

$$c^* = \operatorname{argmin}_{c \in \mathcal{C}} \mathbb{E} \left(\frac{1}{T+1} \sum_{t=0}^T \frac{\|\mathbf{q}(t)\|_1}{|\mathcal{V}(t)|} \right) \quad (1a)$$

Schedule Scheduler

$$s.t. \quad \hat{\mathbf{v}}(t) = c(\mathcal{G}(t), \mathbf{q}(t), \mathbf{r}(t)), \quad \text{Network state} \quad (1b)$$

$$q_v(t+1) = \begin{cases} q_v(t) + a_v(t) & \text{if } v \notin \hat{\mathbf{v}}(t), \\ q_v(t) + a_v(t) - \min(r_v(t), q_v(t)) & \text{if } v \in \hat{\mathbf{v}}(t), \end{cases} \quad (1c)$$

Queueing state
transition

where both constraints hold for every time $t = 0, \dots, T$ and the second constraint holds for all $v \in \mathcal{V}$.

New arrivals

Departures

Average queue length across
time and network (links)

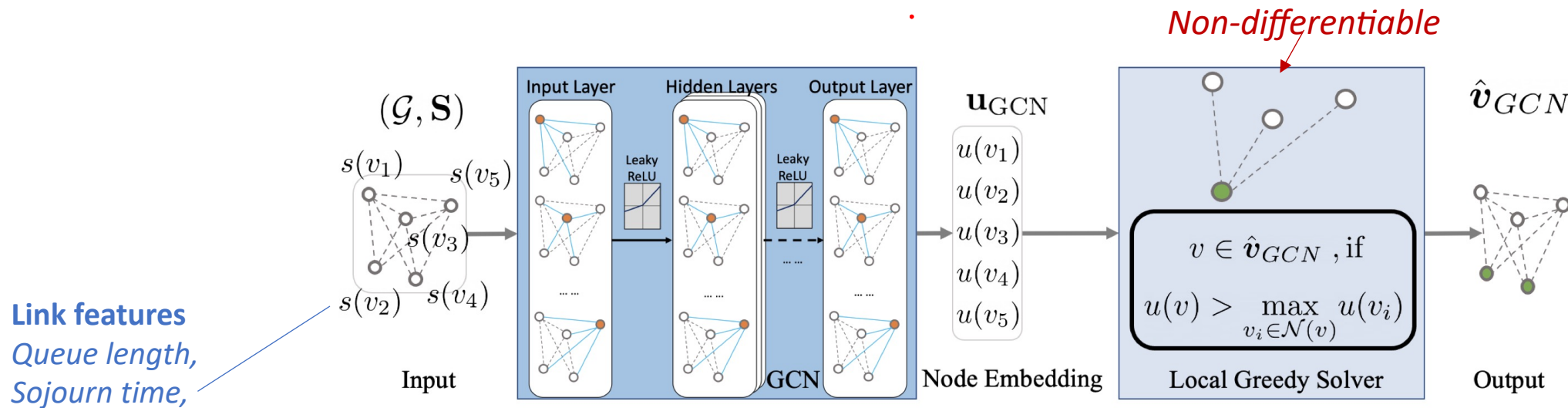
* Robin A Moser and Gábor Tardos. A constructive proof of the general Lovász local lemma. *Journal of the ACM (JACM)*, 57(2):1–15, 2010.

Existing approaches to delay-oriented scheduling

Approach + papers	Distributed	Orthogonal Constraint	Scalability	Topology	Heuristic
Constrained optimization Set delay as constraint [Jaramillo 2011, Hou 2010]	No	Hard	Poor	Yes	N.A.
Delay-aware per-link utility functions virtual queues of congestion [Xue 2012], sojourn time [Hai 2018], age-of-information [Hsu 2017]	Yes	Hard	Good	No	Greedy
Machine Learning only MLP outputs binary decisions [Lee 2021]	Yes	Soft	Poor	Explicit	N.A.
Machine Learning + Heuristic MLP outputs utility [Gupta 2020] MLPs (Multiagent) output biases [Gao 2017]	No [Gupta 2020] Yes [Gao 2017]	Hard	Poor	Implicit	Greedy
[Ours] Graph Convolutional Neural Network + Distributed Greedy Heuristic	Yes	Hard	Good	Explicit	Greedy

Downstream Pipeline

[Zhao 2021]



[Joo 2012]

$$\mathbf{X}^l = \sigma(\mathbf{X}^{l-1} \Theta_0^l + \mathcal{L} \mathbf{X}^{l-1} \Theta_1^l), l \in \{1, \dots, L\},$$

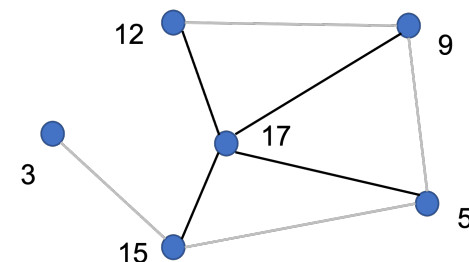
$$L = 1, s(v) = q(v)r(v)$$

$$u(v) = s(v) \theta_0 + \left(s(v) - \sum_{v_i \in \mathcal{N}(v)} \frac{s(v_i)}{\sqrt{d(v)d(v_i)}} \right) \theta_1,$$

$$\mathcal{O}(L + \log |\mathcal{V}|)$$

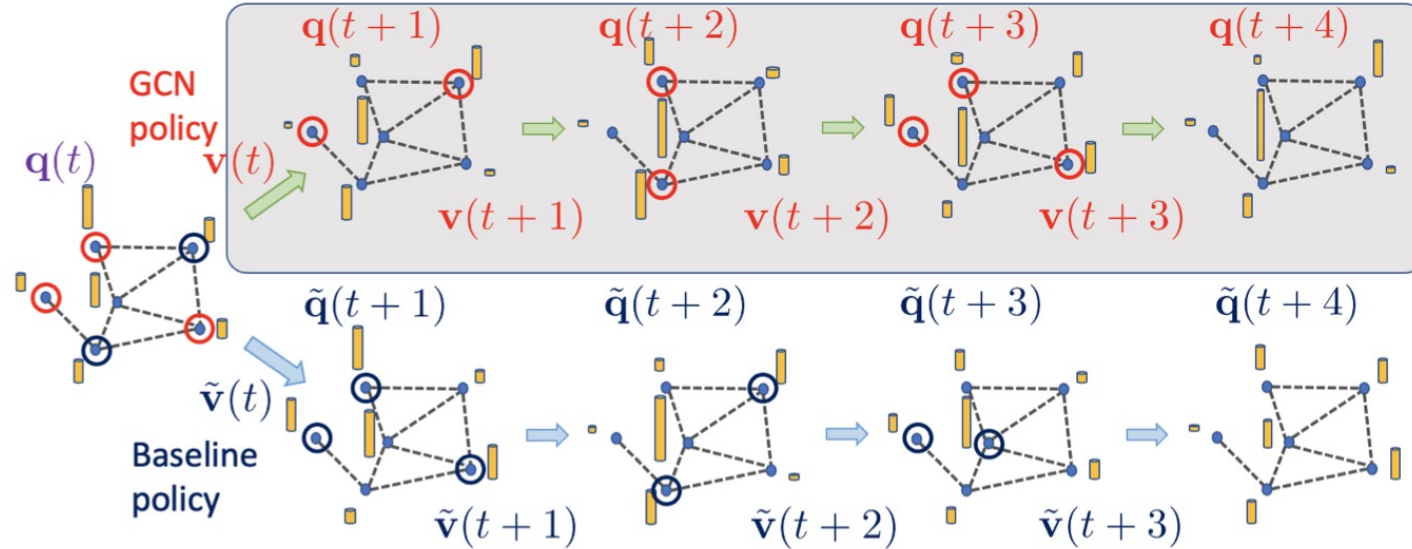
$$\hat{\mathbf{v}}_{Gr} \leftarrow \hat{\mathbf{v}}_{Gr} \cup \left\{ v \mid u(v) > \max_{v_i \in \mathcal{N}(v)} u(v_i), \text{ for all } v \in \mathcal{V}' \right\},$$

$$\mathcal{G}'(\mathcal{V}', \mathcal{E}') \leftarrow \mathcal{G}'(\mathcal{V}', \mathcal{E}') \setminus (\hat{\mathbf{v}}_{Gr} \cup \mathcal{N}(\hat{\mathbf{v}}_{Gr})),$$



Reward by K-step lookahead scheduling

Virtual environment
of scheduling



Schedule on
each step is
different

Stochastic estimation of return

$$\rho(v, t) = \begin{cases} \varphi \left(\frac{\sum_{k=1}^K \|\tilde{\mathbf{q}}(t+k)\|_1}{\sum_{k=1}^K \|\mathbf{q}(t+k)\|_1} \right), & v \in \hat{\mathbf{v}}_{\text{GCN}}(t) \\ u_{\text{GCN}}(v, t), & v \notin \hat{\mathbf{v}}_{\text{GCN}}(t) \end{cases}$$

Customized reinforcement
learning [Zhao 2021]

$$\ell(\omega; \mathcal{G}(t), \mathbf{S}(t)) = |\mathcal{V}|^{-\frac{1}{2}} \|\mathbf{u}_{\text{GCN}}(t) - \boldsymbol{\rho}(t)\|_2.$$

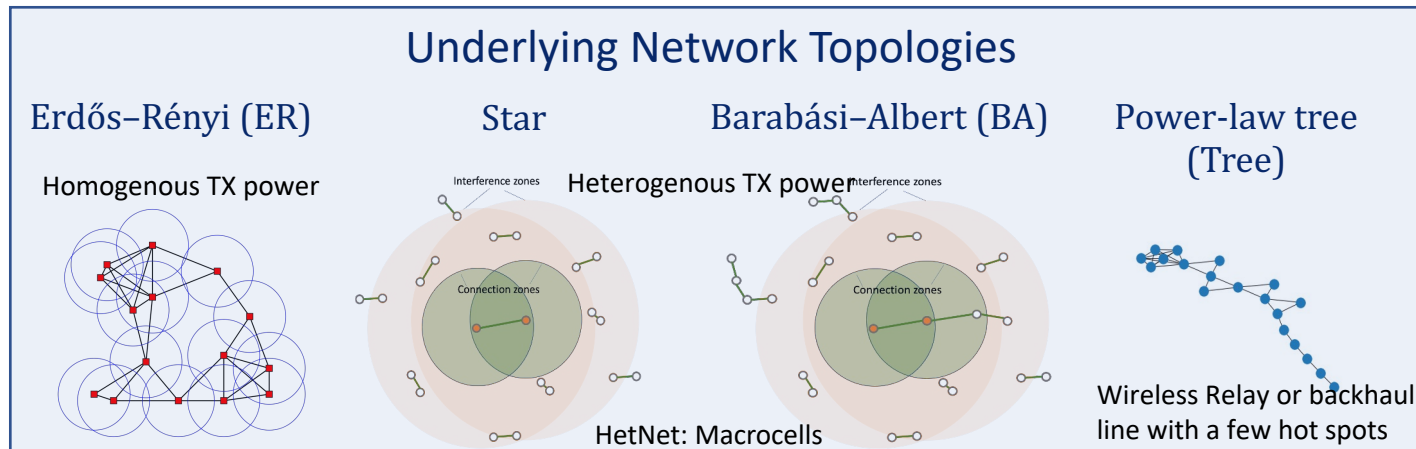
$$\varphi(x) = x$$

$$\varphi(x) = H(x - 1).$$

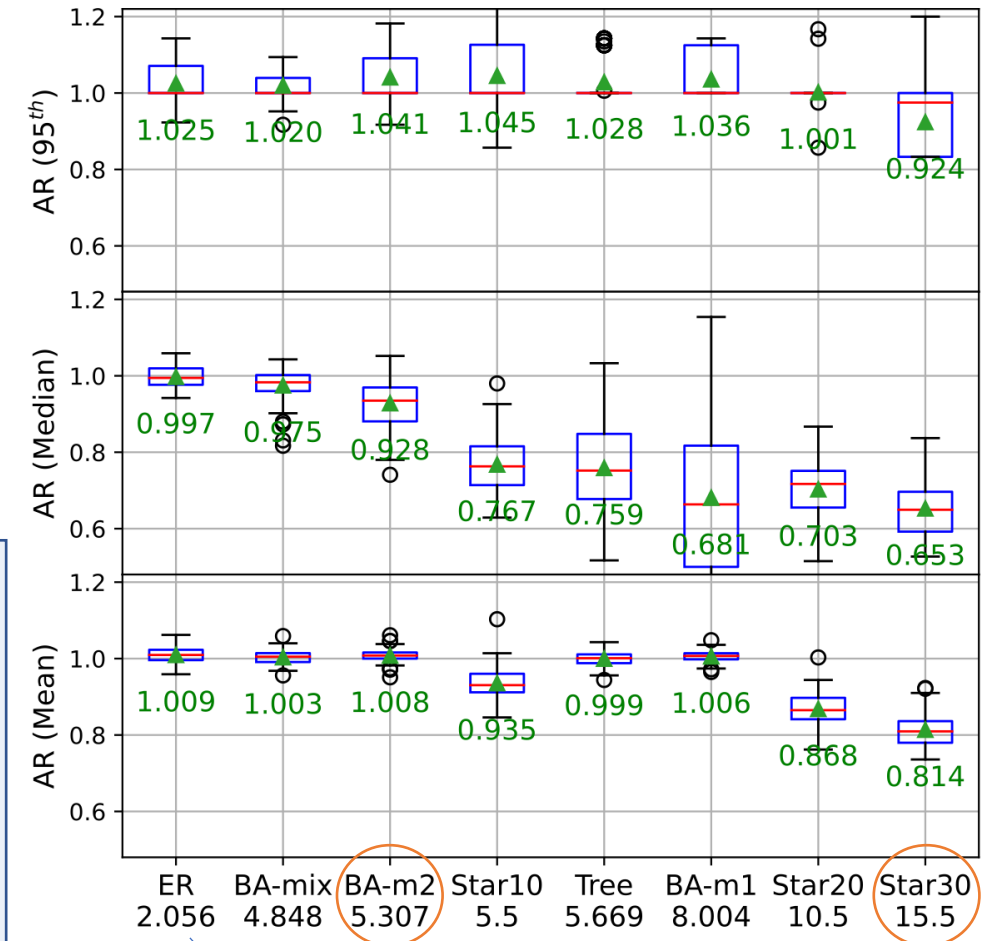
Zhao, Z., Verma, G., Rao, C., Swami, A. and Segarra, S., 2021. Link scheduling using graph neural networks. *arXiv preprint arXiv:2109.05536*.

Queue lengths across topological distributions

- Scheduler
 - GCN $L = 1, s(v) = q(v)r(v)$
 - Baseline: local greedy solver [Joo 2012]
- Traffic
 - 1-hop link, Poisson arrival, clipped normal link rate
 - Light to moderate traffic load
- Training
 - Conflict graphs: 80% Star30 + 20% BA-m2
- Small-to-median sized networks (50, 70, ..., 300 links)



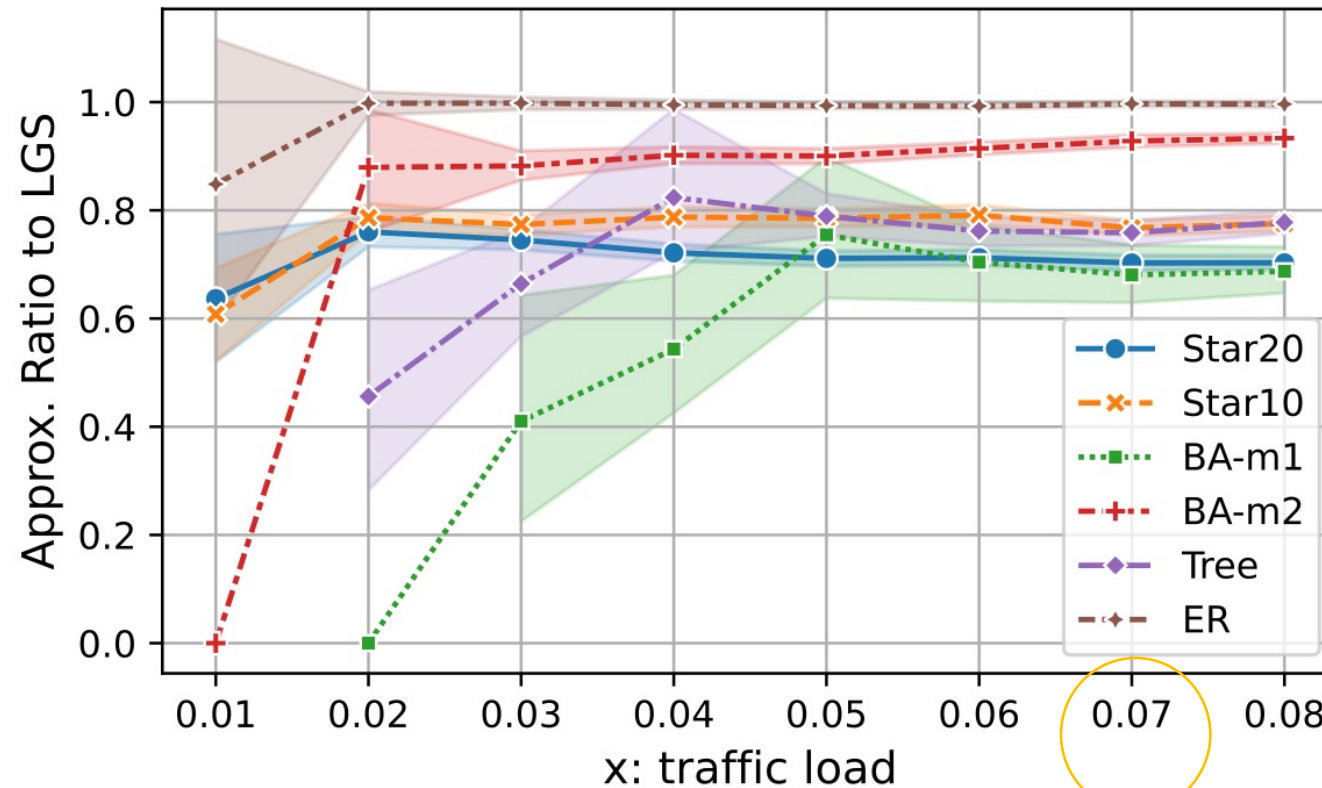
Improved latency on concentrated conflict graphs



Peak to average node degree

Training graph models

Median backlogs across traffic loads



Consistent improvement across traffic loads

$$\mathbb{E}_{v \in \mathcal{V}, t \leq T} \left(\frac{a(v, t)}{r(v, t)} \right)$$

Conclusion & future work

- GCN-enhanced distributed scheduler
 - *Fully distributed solution*
 - *Hard constraint on orthogonal multiple access*
 - *Constant additional overhead*
 - Exploit **topology**
 - Generalize across graph distribution, sizes, and traffic loads.
 - Improves latency on networks with heterogenous transmit power
- Integration of delay-aware and topology-aware utility
- Principled learning approach for non-differentiable pipeline

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